



LINEAR SYSTEMS (034032)

TUTORIAL 1

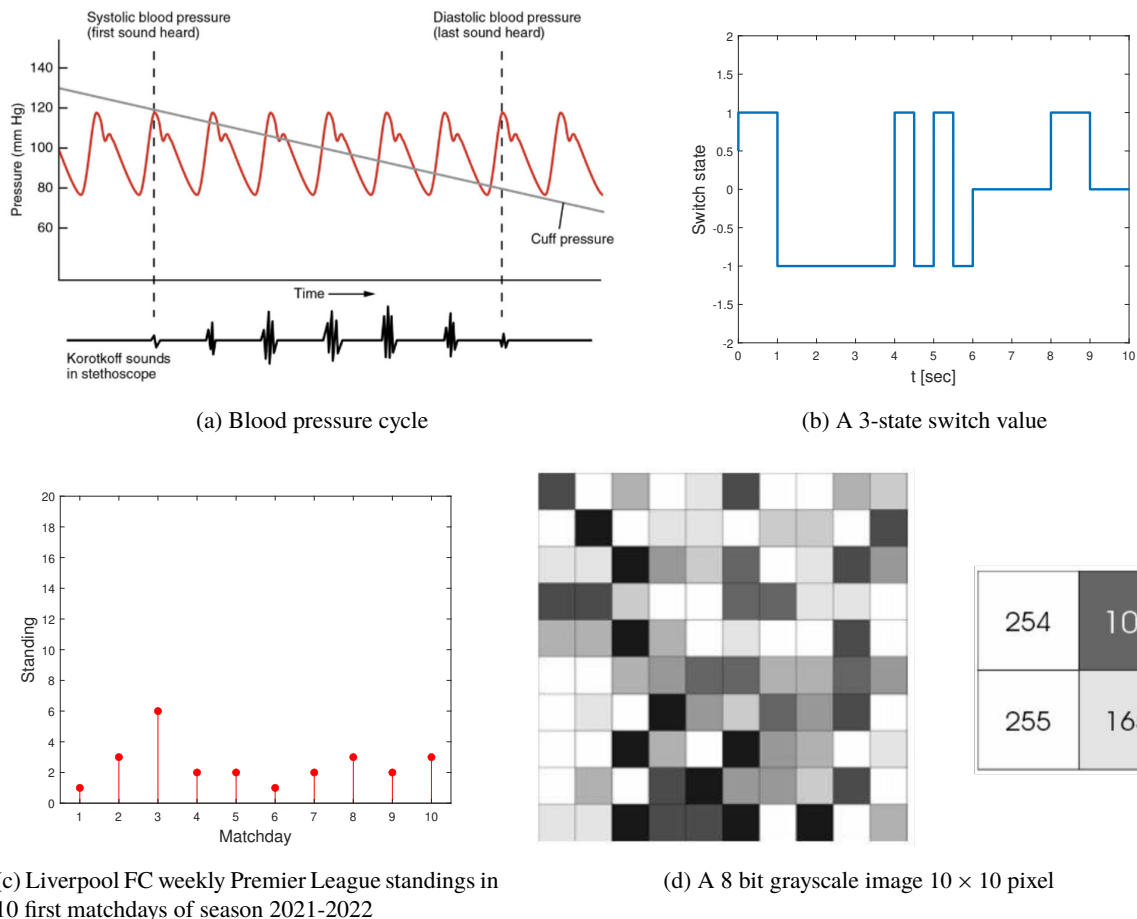


Fig. 1: Signals for Question 1

Question 1. Describe properties (domains and codomains) of the signals in Fig. 1.

Question 2. Consider a mass rotating inside a cylinder depicted in Fig. 2. The mass, whose moment of inertia is J , is attached to a torsion spring, whose torsion coefficient is k_T . An external torque τ acts on the mass and friction between the mass and the cylinder is assumed to generate a viscous friction torque $\tau_c = -c_T \dot{\theta}$. Find the relation between input signal τ and output signal θ .

Question 3. Consider the following system described in Fig. 3.

The input is a force f acting on the cart m_1 , which is constrained to slide without friction in the horizontal direction. A pendulum, mass m_2 , length l , is attached to the cart and is free to rotate around its axis. The outputs are the position of the cart x and the angle of the pendulum θ . Write the equations of motion.

Norms

Norms are a class of functions that enable us to quantify the size of a vector by assigning a nonnegative

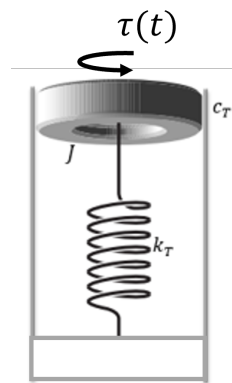


Fig. 2: Spring mass damper system.

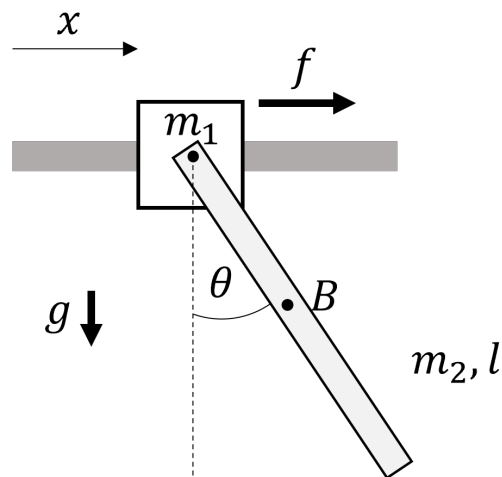


Fig. 3: Cart and pendulum

scalar to each vector.

Properties of a Norm:

1. Positive Definiteness: It should always be nonnegative. It is zero if and only if the vector is zero, i.e., zero vector. $\|v\| \geq 0$ and $\|v\| = 0 \Leftrightarrow v = 0$
2. Homogeneity: Multiplying a vector by a scalar multiplies the vector's norm by the scalar's absolute value. $\|\alpha v\| = |\alpha| \|v\|$
3. Triangle inequality: The norm of a sum of two vectors is no more than the sum of their norms. $\|v\| + \|u\| \geq \|v + u\|$

Two useful norms are

1. Norm-2: $\|x\|_2 = \sqrt{\sum_{i=1}^n |x_i|^2}$
2. Norm-infinity: $\|x\|_\infty = \max |x_i|$

Question 4. Calculate $\|x\|_2$ and $\|x\|_\infty$ where

1. $x = [x_1, x_2, x_3]$ and $|x_2| \geq |x_1| \geq |x_3|$

2. $x = [1, 0, 0]$

3. $x = [1, 1, 1]$

Question 5. Find the sets of a 2D vector x such that $\|x\|_2 = 1$ and $\|x\|_\infty = 1$