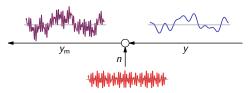
Example 0

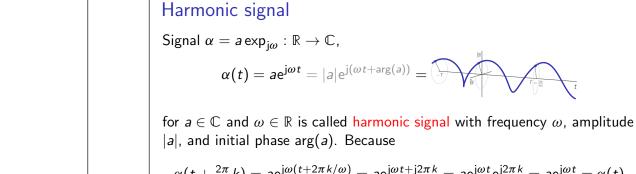


A signal y is observed via an imperfect sensor, where the measured signal is

 $y_{\rm m} = y + n$

for (unknown) additive noise *n* reflecting sensor inaccuracies. The question then is

- how signal (y) can be recovered from its corrupt measurements (y_m) ? This might appear a tough task, for there is no way we can separate y from *n* in the time domain . . .



$$\alpha(t + \frac{2\pi}{\omega}k) = a e^{j\omega(t + 2\pi k/\omega)} = a e^{j\omega t + j2\pi k} = a e^{j\omega t} e^{j2\pi k} = a e^{j\omega t} = \alpha(t)$$

 $i\omega t i 2\pi k$

4/4

for all $k \in \mathbb{Z}$, the harmonic signal is $\frac{2\pi}{|\omega|}$ -periodic (ω may be negative).

Euler's formula $e^{j\theta} = \cos \theta + j \sin \theta$ can be used to connect the (complex) harmonic signal with real sinusoids:

$$\sin(\omega t + \phi) = ae^{j\omega t} + \overline{a}e^{-j\omega t}, \quad a = 0.5e^{j(\phi - \pi/2)}$$

(harmonics with ω and $-\omega$ come together in real-valued signals).

Linear Systems (034032) lecture no. 3

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 $\mathbf{\tilde{N}}$

Outline

Fourier series

Harmonic signal (contd)

The signal $a_1 \exp_{j\omega_1}$ is said to be faster (slower) than $a_2 \exp_{j\omega_2}$ if $|\omega_1| > |\omega_2|$ $(|\omega_1| < |\omega_2|)$. Indeed,

$$x_1 = \overbrace{\tau_t}^{la}$$
 is faster than $x_2 = \overbrace{\tau_t}^{la}$

just because

$$rac{|\dot{x}_1(t)|}{|x_1(t)|} = |\omega_1| > |\omega_2| = rac{|\dot{x}_2(t)|}{|x_2(t)|}, \quad orall t$$

.

Note that there is no "the fastest" continuous-time signals.

Power

$$P_{a\exp_{j\omega}} = \frac{1}{T} \int_0^T |ae^{j\omega t}|^2 dt = \frac{|a|^2}{T} \int_0^T dt = |a|^2$$

Example 1 Let $x = \sum_{i \in T} \mathbb{S}_{iT} \operatorname{tent}_{T/2} = \sum_{i \in T} \mathbb{S}_{iT}$ Fourier coefficients: $X[k] = \frac{1}{T} \int_{-T/2}^{T/2} \operatorname{tent}_{T/2}(t) \mathrm{e}^{-\mathrm{j}\omega_0 kt} \mathrm{d}t = \frac{1}{T} \int_{-T/2}^{T/2} \left(1 - \frac{2|t|}{T}\right) \mathrm{e}^{-\mathrm{j}\omega_0 kt} \mathrm{d}t$ $=\frac{1}{T}\left(\int_{-T/2}^{0}\left(1+\frac{2t}{T}\right)e^{-j\omega_{0}kt}dt+\int_{0}^{T/2}\left(1-\frac{2t}{T}\right)e^{-j\omega_{0}kt}dt\right)$ $1 ((1 - e^{j\pi k} + j\pi k)T) (1 - e^{-j\pi k} - j\pi k)T$

$$= \frac{1}{T} \left(\frac{1}{2\pi^2 k^2} + \frac{1}{2\pi^2 k^2} \right)$$
$$= \frac{1 - \cos(\pi k)}{\pi^2 k^2} = \frac{1 - (-1)^k}{\pi^2 k^2} = \begin{cases} 1/2 & \text{if } k = 0\\ 0 & \text{if } k \neq 0 \text{ and is even}\\ 2/(\pi k)^2 & \text{if } k \text{ is odd} \end{cases}$$

Fourier series of continuous signals

If $x : \mathbb{R} \to \mathbb{R}$ is *T*-periodic and continuous, then at every *t*

$$X(t) = \sum_{k \in \mathbb{Z}} X[k] \mathrm{e}^{\mathrm{j}\omega_0 k t} = \sum_{k \in \mathbb{Z}} X[k] \mathrm{e}^{\mathrm{j}(2\pi/T)k t},$$

where

$$X[k] = \frac{1}{T} \int_{-T/2}^{T/2} x(t) \mathrm{e}^{-\mathrm{j}\omega_0 kt} \mathrm{d}t = \frac{1}{T} \int_{a}^{a+T} x(t) \mathrm{e}^{-\mathrm{j}\omega_0 kt} \mathrm{d}t \in \mathbb{C}$$

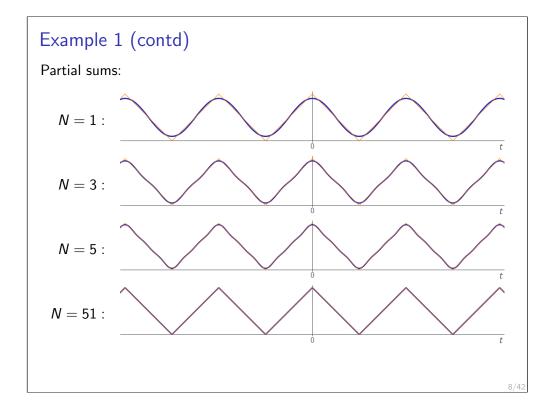
are known as Fourier coefficients of x and

$$\omega_0 := \frac{2\pi}{T}$$

is known as its fundamental frequency. The *T*-periodic $x_N : \mathbb{R} \to \mathbb{R}$ with

$$x_N(t) := \sum_{k=-N}^N X[k] \mathrm{e}^{\mathrm{j}\omega_0 k t}$$

is known as a partial sum of the Fourier series of x.



Example 2
Let

$$s(t) = \begin{cases} 8t^{2} & \text{if } 0 \le t \le 1/4 \\ -8t^{2} + 8t - 1 & \text{if } 1/4 \le t \le 3/4 \\ 8(t - 1)^{2} & \text{if } 3/4 \le t \ge 1 \\ 0 & \text{otherwise} \end{cases}$$
and define *T*-periodic

$$x = \sum_{i \in \mathbb{Z}} \mathbb{S}_{iT} \mathbb{P}_{1/T} s = \underbrace{\int_{-T/2}^{1} \int_{0}^{1} \int_{T/2}^{1} \int_{0}^{T} \int_{0}^{T} f(t/T) e^{-j\omega_{0}kt} dt$$
Fourier coefficients:

$$X[k] = \frac{1}{T} \int_{-T/2}^{T/2} x(t) e^{-j\omega_{0}kt} dt = \frac{1}{T} \int_{0}^{T} s(t/T) e^{-j\omega_{0}kt} dt$$

$$= \frac{8(-1)^{k} \sin(\pi k/2)}{\pi^{3} k^{3}} = \begin{cases} 1/2 & \text{if } k = 0 \\ 0 & \text{if } k \neq 0 \text{ and is even} \\ 8(-1)^{(k+1)/2}/(\pi k)^{3} & \text{if } k \text{ is odd} \end{cases}$$

Piecewise-smooth signals

A *T*-periodic signal x is said to be piecewise smooth if it's differentiable and has continuous derivative everywhere on [0, T] with a possible exception of a finite number of distinct t_i , at which $x(t_i^+)$, $x(t_i^-)$, $\dot{x}(t_i^+)$ and $\dot{x}(t_i^-)$ exist in the sense of the existence of

9/42

11/42

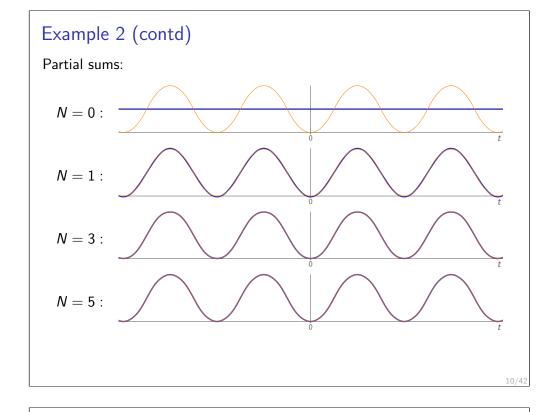
$$x(t_i^+) := \lim_{h \downarrow 0} x(t_i + h), \quad x(t_i^-) := \lim_{h \downarrow 0} x(t_i - h), \quad \text{etc}$$

Example:



for $\eta \in (0, 1)$.

Remark The notion extends to non-periodic functions, which are ∞ -periodic, in a sense. In that case we need continuous derivatives everywhere except a counted number points t_i , at which $x(t_i^-)$, $x(t_i^-)$, $\dot{x}(t_i^+)$ and $\dot{x}(t_i^-)$ exist.



Fourier series of piecewise-smooth signals Everything you always wanted to know about Fourier peculiarities^{*} (*but were afraid to ask) If $x : \mathbb{R} \to \mathbb{R}$ is *T*-periodic and piecewise smooth, then at every *t*

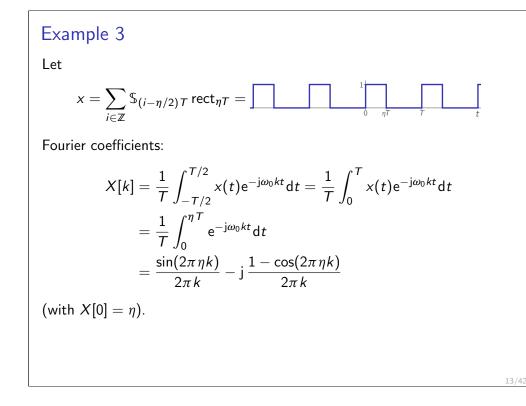
$$\frac{x(t^+) + x(t^-)}{2} = \sum_{k \in \mathbb{Z}} X[k] \mathrm{e}^{\mathrm{j}\omega_0 k \mathrm{i}}$$

Let $X:\mathbb{Z}\to\mathbb{C}$ be the signal comprising the Fourier coefficients. If $X\in\ell_1$, then

$$\lim_{N\to\infty} x_N(t) = \lim_{N\to\infty} \sum_{k=-N}^N X[k] e^{j\omega_0 kt}$$

converges to x(t) at every t and the limit is necessarily continuous $X \notin \ell_1$, then the partial sum converges only in the ℓ_2 sense, i.e.

$$\lim_{\mathsf{V}\to\infty} \|x-x_{\mathsf{N}}\|_2 = 0$$



Gibbs phenomenon

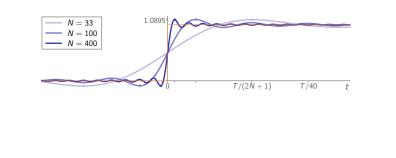
Near every discontinuity point of x,

$$x_{N}\left(t+\frac{T}{2N+1}\right)-x(t^{+})\xrightarrow{N\to\infty}\left(\underbrace{\frac{1}{\pi}\int_{0}^{\pi}\operatorname{sinc}(t)\mathrm{d}t-\frac{1}{2}}_{\approx0.089549}\right)\left(x(t^{+})-x(t^{-})\right)$$

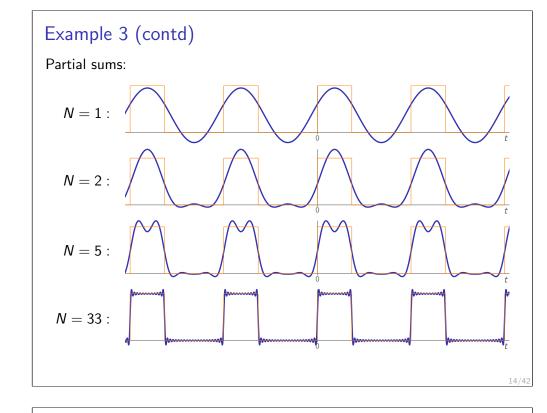
and

$$x_N(t-rac{T}{2N+1})-x(t^-) \xrightarrow{N o \infty} \left(rac{1}{\pi} \int_0^{\pi} \operatorname{sinc}(t) \mathrm{d}t - rac{1}{2}
ight)(x(t^-)-x(t^+))$$

like in



15/42



Some properties					
	property	signal	Fourier coefficients		
	linearity	$x = a_1 x_1 + a_2 x_2$	$X[k] = a_1 X_1[k] + a_2 X_2[k]$		
	time shift	$y = \$_{\tau} x$	$Y[k] = \mathrm{e}^{\mathrm{j}\omega_0\tau k}X[k]$		
	time reversal	$y = \mathbb{P}_{-1}x$	Y[k] = X[-k]		
	conjugation	$y = \overline{x}$	$Y[k] = \overline{X[-k]}$		
	convolution	z = x * y	Z[k] = X[k]Y[k]		

Consequently, if x is real-valued (codomain is \mathbb{R}), then $X[k] = \overline{X[-k]}$ - i.e. |X[k]| = |X[-k]| and $\arg(X[k]) = -\arg(X[k])$ and all information is in X[k] for $k \in \mathbb{Z}_+$.

Remember, $(\mathbb{S}_{\tau}x)(t) = x(t+\tau)$ and $(\mathbb{P}_{\varsigma}x)(t) = x(\varsigma t)$.

Meaning

The expansion

$$x(t) = \sum_{k \in \mathbb{Z}} X[k] \mathrm{e}^{\mathrm{j}\omega_0 k t}$$

means that every T-periodic x is a superposition of elementary harmonics

$$lpha_{x,k}(t) := X[k] \mathrm{e}^{\mathrm{j}\omega_0 k t}$$

whose frequencies are multiples of the fundamental frequency $\omega_0 = 2\pi/T$.

The discrete signal $X : \mathbb{Z} \to \mathbb{C}$ comprised of Fourier coefficients is known as the (line) spectrum of x. In other words,

- T-periodic x can be equivalently represented by the discrete-time X, known as the frequency-domain representation of x.

Parseval identity: meaning

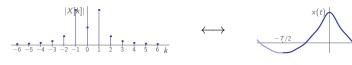
The Parseval identity effectively says that

$$P_x = \sum_{k \in \mathbb{Z}} P_{\alpha_{x,k}}$$

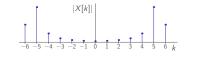
i.e. the power of x equals the sum of powers of all its harmonic components in the expansion $x = \sum_{k} \alpha_{x,k}$. This, in turn, implies that

 $-\,$ harmonics with largest amplitudes dominate the behavior of x

- if dominating harmonics are low, x is slow



- if dominating harmonics are high, x is fast



Parseval identity

Theorem

F

17/42

If T-periodic x is piecewise smooth, then

$$P_x = \sum_{k \in \mathbb{Z}} |X[k]|^2.$$

Proof: Because
$$|c|^2 = c\overline{c}$$
,

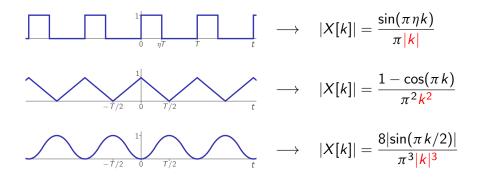
$$P_x = \frac{1}{T} \int_{-T/2}^{T/2} x(t) \overline{x(t)} dt = \frac{1}{T} \int_{-T/2}^{T/2} x(t) \overline{\left(\sum_{k \in \mathbb{Z}} X[k] e^{j\omega_0 kt}\right)} dt$$

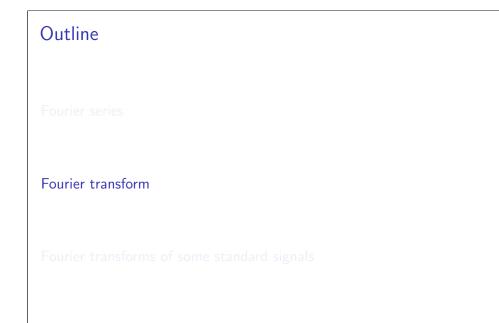
$$= \sum_{k \in \mathbb{Z}} \left(\frac{1}{T} \int_{-T/2}^{T/2} x(t) e^{-j\omega_0 kt}\right) dt \overline{X[k]}$$

$$= \sum_{k \in \mathbb{Z}} X[k] \overline{X[k]} = \sum_{k \in \mathbb{Z}} |X[k]|^2$$

Decay of Fourier coefficients

In general, the faster |X[k]| decays as |k| grows, the smoother x is, because faster harmonics have then smaller effect on x, cf.





Meaning

Similarly to the Fourier series, the relation

$$x(t) = rac{1}{2\pi} \int_{\mathbb{R}} X(\mathrm{j}\omega) \mathrm{e}^{\mathrm{j}\omega t} \mathrm{d}\omega$$

means that

- aperiodic x is also a superposition of elementary harmonics $\alpha_{x,\omega}$, with $\alpha_{x,\omega}(t) = \frac{1}{2\pi} X(j\omega) e^{j\omega t}$,

now with a continuum of frequencies ω (measured in radians per time unit).

The signal X is then called the spectrum or frequency-domain representation of x, with the amplitude spectrum |X| and the phase spectrum $\arg(X)$.

The value X(j0) = X(0) is the average of x over all its domain, i.e. \mathbb{R} .

Definition

The Fourier transform $\mathfrak{F}{x}$ of a signal x is the signal $X : \mathbb{R} \to \mathbb{C}$ such that

$$X(j\omega) = (\mathfrak{F}\{x\})(j\omega) := \int_{\mathbb{R}} x(t) e^{-j\omega t} dt$$

('j ω ' is used for a technical reason to be clarified one day). It is well defined if $x \in L_1$ (plus some mild technical assumptions) and then

$$x(t) = \frac{1}{2\pi} \int_{\mathbb{R}} X(j\omega) e^{j\omega t} d\omega =: (\mathfrak{F}^{-1}\{X\})(t)$$

at every t. The latter integral is referred to as the inverse Fourier transform.

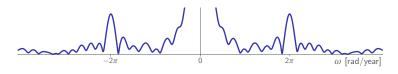
If $x \in L_2$, then the Fourier integral converges only in the (weaker) L_2 -norm sense, $||x - \mathfrak{F}^{-1}\{X_N\}||_2 \to 0$. We can then still extend the transform to L_2 signals. The use of distributions facilitates extending the Fourier transform to yet wider classes of signals.

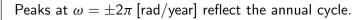
Example 1

Kinneret water level from Sep 1993 to Sep 2004

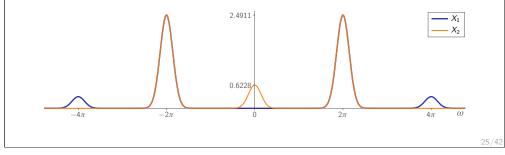


and its amplitude spectrum (with $h_{red,up}$ taken as zero)



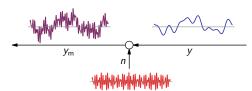


are hardly distinguishable in the time domain. But they are quite different, e.g. the average $\int_{\mathbb{R}} x_1(t) dt \approx 0 \neq 0.62 \approx \int_{\mathbb{R}} x_2(t) dt$. These differences are visible in their spectra



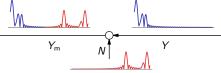
Basic properties					
	property	time domain	frequency domain		
_	linearity	$x = a_1 x_1 + a_2 x_2$	$X(j\omega) = a_1 X_1(j\omega) + a_2 X_2(j\omega)$		
	duality	$y = X _{\omega = t}$	$Y(j\omega) = 2\pi x(-\omega)$		
	time shift	$y = S_{\tau} x$	$Y(\mathrm{j}\omega)=\mathrm{e}^{\mathrm{j}\omega au}X(\mathrm{j}\omega)$		
	time scaling	$y = \mathbb{P}_{\varsigma} x$	$Y(j\omega) = \frac{1}{ \varsigma }X(j\omega/\varsigma)$		
	conjugation	$y = \overline{x}$	$Y(j\omega) = \overline{X(-j\omega)}$		
	modulation	$y = x \exp_{j\omega_0}$	$Y(j\omega) = X(j(\omega - \omega_0))$		
	$differentiation^2$	$y = \dot{x}$	$Y(j\omega) = j\omega X(j\omega)$		
	convolution	z = x * y	$Z(j\omega) = X(j\omega)Y(j\omega)$		
	provided all involved transforms exist				
2	² If $\lim_{t \to \pm \infty} x(t) = 0$, which is normally the case for $x \in L_1$.				

Example 0 (contd)



The question was

- how signal (y) can be recovered from its corrupt measurements (y_m) ? This might appear a tough task, for there is no way we can separate y from n in the time domain... But in the frequency domain these signals are well separated,



suggesting that the frequency-domain viewpoint is valuable¹.

 $^1\mbox{However},$ we yet to learn how to fully exploit it efficiently.

Basic properties: duality
If
$$y = X|_{\omega=t}$$
, i.e. $y(t) = X(jt)$, where $X = \mathfrak{F}\{x\}$, then
 $Y(j\omega) = \int_{\mathbb{R}} X(jt) e^{-j\omega t} dt \Big|_{t=\tilde{\omega}} = 2\pi \left(\frac{1}{2\pi} \int_{\mathbb{R}} X(j\tilde{\omega}) e^{j\tilde{\omega}(-\omega)} d\tilde{\omega}\right)$
 $= 2\pi x(-\omega)$

because

27/42

$$\mathbf{x}(t) = rac{1}{2\pi} \int_{\mathbb{R}} X(\mathbf{j}\omega) \mathrm{e}^{\mathbf{j}\omega t} \mathrm{d}\omega$$

Basic properties: time shift
If
$$y = \$_{\tau} x$$
, i.e. $y(t) = x(t + \tau)$, then

$$Y(j\omega) = \int_{\mathbb{R}} x(t + \tau) e^{-j\omega t} dt \Big|_{s=t+\tau} = \int_{\mathbb{R}} x(s) e^{-j\omega(s-\tau)} ds$$

$$= e^{j\omega \tau} \int_{\mathbb{R}} x(s) e^{-j\omega s} ds$$

$$= e^{j\omega \tau} X(j\omega)$$

Basic properties: conjugation

If $y = \overline{x}$ (complex conjugate), then

$$Y(j\omega) = \int_{\mathbb{R}} \overline{x(t)} e^{-j\omega t} dt = \int_{\mathbb{R}} \overline{x(t)} \overline{e^{-j\omega t}} dt = \overline{\int_{\mathbb{R}} x(t)} e^{j\omega t} dt$$
$$= \overline{\int_{\mathbb{R}} x(t)} e^{-j(-\omega)t} dt$$
$$= \overline{X(-j\omega)}$$

If $x : \mathbb{R} \to \mathbb{R}$ (real valued), then $y = \overline{x} = x$, so that

 $X(j\omega) = \overline{X(-j\omega)},$

i.e. we may look only at the spectrum over $\omega \ge 0$. If, in addition, $x = \mathbb{P}_{-1}x$ (such functions are called *even*), then by the time scaling property

$$X(j\omega) = X(-j\omega) = \overline{X(-j\omega)}.$$

Hence, if x is real valued and even, then X is real valued and even as well.

Basic properties: time scaling

$$f(y) = \mathbb{P}_{\varsigma}x, \text{ i.e. } y(t) = x(\varsigma t), \text{ then}$$

$$\begin{aligned}
\gamma(j\omega) &= \int_{\mathbb{R}} x(\varsigma t) e^{-j\omega t} dt \Big|_{s=\varsigma t} = \begin{cases} \int_{-\infty}^{\infty} x(\varsigma) e^{-j\omega s/\varsigma} d(s/\varsigma) & \text{ if } \varsigma > 0 \\ \int_{-\infty}^{\infty} x(\varsigma) e^{-j\omega s/\varsigma} d(s/\varsigma) & \text{ if } \varsigma < 0 \end{cases}$$

$$= \begin{cases} \frac{1}{\varsigma} \int_{-\infty}^{\infty} x(\varsigma) e^{-j(\omega/\varsigma)s} ds & \text{ if } \varsigma > 0 \\ -\frac{1}{\varsigma} \int_{-\infty}^{\infty} x(\varsigma) e^{-j(\omega/\varsigma)s} ds & \text{ if } \varsigma < 0 \end{cases}$$

$$= \frac{1}{|\varsigma|} \int_{\mathbb{R}} x(\varsigma) e^{-j(\omega/\varsigma)s} ds$$

$$= \frac{1}{|\varsigma|} X(j\omega/\varsigma)$$

Basic properties: modulation If $y = x \exp_{j\omega_0}$, i.e. $y(t) = x(t)e^{j\omega_0 t}$, then $Y(j\omega) = \int_{\mathbb{R}} x(t)e^{j\omega_0 t}e^{-j\omega t}dt = \int_{\mathbb{R}} x(t)e^{-j(\omega-\omega_0)t}dt$ $= X(j(\omega - \omega_0))$

By linearity and modulation, if

29/42

31/42

$$y(t) = \sin(\omega_0 t + \phi)x(t) = a e^{j\omega_0 t}x(t) + \overline{a} e^{-j\omega_0 t}x(t),$$

where $a := 0.5 e^{j(\phi - \pi/2)}$, then

$$Y(j\omega) = aX(j(\omega - \omega_0)) + \overline{a}X(j(\omega + \omega_0))$$

Basic properties: differentiation If $y = \dot{x}$, i.e. $y(t) = \frac{d}{dt}x(t)$, and $\lim_{t \to \pm \infty} x(t) = 0$, then $Y(j\omega) = \int_{\mathbb{R}} \dot{x}(t)e^{-j\omega t}dt = x(t)e^{-j\omega t}\Big|_{-\infty}^{\infty} - \int_{\mathbb{R}} x(s)(\frac{d}{dt}e^{-j\omega t})dt$ $= j\omega \int_{\mathbb{R}} x(t)e^{-j\omega t}dt$ $= j\omega X(j\omega)$

because

$$\int_{a}^{b} \dot{f}(t)g(t)dt = f(t)g(t)\Big|_{a}^{b} - \int_{a}^{b} f(t)\dot{g}(t)dt$$

(integration by parts).

Similar arguments apply to the inverse Fourier, so

 $y(t) = -jtx(t) \iff Y(j\omega) = \frac{d}{d\omega}X(j\omega)$

Parseval's theorem

Theorem

If $x \in L_1 \cap L_2$, then

$$|x||_{2}^{2} = \int_{\mathbb{R}} |x(t)|^{2} dt = \frac{1}{2\pi} \int_{\mathbb{R}} |X(j\omega)|^{2} d\omega = \frac{1}{2\pi} ||X||_{2}^{2}$$

In other words,

- the energy of x equals the energy of $\mathfrak{F}\{x\}$, modulo the factor $1/(2\pi)$.

Basic properties: convolution If z = x * y, then $Z(j\omega) = \int_{\mathbb{R}} \int_{\mathbb{R}} x(t-s)y(s)dse^{-j\omega t}dt = \int_{\mathbb{R}} \int_{\mathbb{R}} x(t-s)y(s)e^{-j\omega t}dtds$ $= \int_{\mathbb{R}} \int_{\mathbb{R}} x(t-s)e^{-j\omega t}dty(s)ds$ $= \int_{\mathbb{R}} X(j\omega)e^{-j\omega s}y(s)ds \qquad (by the time shift property)$ $= X(j\omega) \int_{\mathbb{R}} y(s)e^{-j\omega s}ds$ $= X(j\omega)Y(j\omega)$ the (unproven) fact that $x, y \in L_1 \implies x * y \in L_1$ is required in this proof.

Outline Fourier series Fourier transform Fourier transforms of some standard signals

34/42

Rectangular pulse If x = rect, then $X(j\omega) = \int_{\mathbb{R}} x(t)e^{-j\omega t} dt = \int_{-1/2}^{1/2} e^{-j\omega t} dt = \frac{e^{-j\omega t}}{-j\omega} \Big|_{-1/2}^{1/2} = \frac{e^{j\omega/2} - e^{-j\omega/2}}{j\omega}$ $= \frac{e^{j\omega/2} - e^{-j\omega/2}}{2j\omega/2} = \frac{\sin(\omega/2)}{\omega/2} = \operatorname{sinc}(\omega/2) = \underbrace{\int_{0}^{1/2} \frac{1}{2\pi 4\pi - \omega}}_{0, 2\pi 4\pi - \omega}$ Consequences: - by time scaling, if $y = \text{rect}_{a}$ for some a > 0, then $Y(j\omega) = (\mathfrak{F}[\mathbb{1}_{1/a} \operatorname{rect}])(\omega) = a \operatorname{sinc}(\frac{a}{2}\omega) = a(\mathbb{P}_{1/2} \operatorname{sinc})(\omega)$ - by duality and time scaling, if $y = \mathbb{P}_{1/2} \operatorname{sinc}$ and $z = \mathbb{P}_{\varsigma} \operatorname{sinc}$, then $Y(j\omega) = 2\pi \operatorname{rect}(\omega) \quad \text{and} \quad Z(j\omega) = \frac{\pi}{\varsigma} \operatorname{rect}_{2\varsigma}(\omega)$ (mind that $\operatorname{rect}(-\omega) = \operatorname{rect}(\omega)$ and $\mathbb{P}_{\varsigma} \operatorname{sinc} = \mathbb{P}_{2\varsigma} \mathbb{P}_{1/2} \operatorname{sinc}$).

Triangular pulse

Remember (Lect. 2, Slide 12) that tent = rect * rect. So if x = tent, then

$$X(j\omega) = (\mathfrak{F}\{\text{rect} * \text{rect}\})(j\omega) = \operatorname{sinc}^2(\omega/2) = \underbrace{1}_{0 \ 2\pi \ 4\pi \ \omega}$$

by the convolution property of the Fourier transform.

Consequence:

- by time scaling, if $y = tent_a$ for some a > 0, then

$$Y(j\omega) = (\mathfrak{F}\{\mathbb{P}_{1/a} \operatorname{tent}\})(\omega) = \frac{a \operatorname{sinc}^2(\frac{a}{2}\omega)}{2}$$

Exponent with support in \mathbb{R}_+ If $x = \exp_{\lambda} 1$ for $\lambda \in \mathbb{R}$, then $x \in L_1$ iff $\lambda < 0$ and in that case $X(i_{\lambda}) = \int e^{\lambda t} 1(t) e^{-i\omega t} dt = \int e^{(\lambda - i\omega)t} dt = e^{(\lambda - j\omega)t} dt$

$$X(j\omega) = \int_{\mathbb{R}} e^{\lambda t} \mathbb{1}(t) e^{-j\omega t} dt = \int_{\mathbb{R}_{+}} e^{(\lambda - j\omega)t} dt = \frac{e^{(\lambda - j\omega)t}}{\lambda - j\omega} \Big|_{0}^{\infty} = \frac{1}{j\omega - \lambda}$$

The same formula holds if $\lambda\in\mathbb{C}$ and $\text{Re}\,\lambda<0.$

Consequences:

37/42

 $-\,$ by differentiation with respect to frequency,

$$y(t) = rac{t^n}{n!} \mathrm{e}^{\lambda t} \mathbb{1}(t) \iff Y(\mathrm{j}\omega) = rac{1}{(\mathrm{j}\omega - \lambda)^{n+1}}$$

- by linearity and modulation, if $y(t) = \sin(\omega_0 t + \phi) e^{\lambda t} \mathbb{1}(t)$, then

$$Y(j\omega) = \frac{\omega_0 \cos \phi + (j\omega - \lambda) \sin \phi}{(j\omega - \lambda)^2 + \omega_0^2}$$

Dirac delta (not quite rigorous, still true)

If $x = \delta$, then by the sifting property

$$X(\mathrm{j}\omega)=\int_{\mathbb{R}}\delta(t)\mathrm{e}^{-\mathrm{j}\omega t}\mathrm{d}t=\mathrm{e}^{-\mathrm{j}\omega t}ig|_{t=0}=1$$

i.e. $\mathfrak{F}{\delta}$ contains all harmonics with equal weights, $1/(2\pi)$. Consequences:

– by duality and the fact that $\delta(\omega) = \delta(-\omega)$, if y = 1 (constant), then

$$Y(j\omega) = 2\pi\delta(\omega)$$

- by modulation, if $y = \exp_{j\omega_0}$, then

$$Y(j\omega) = 2\pi\delta(\omega - \omega_0)$$

- by linearity, if $y(t) = \sin(\omega_0 t + \phi)$, then

$$Y(j\omega) = \pi e^{j(\pi/2 - \phi)} \delta(\omega + \omega_0) - \pi e^{j(\pi/2 + \phi)} \delta(\omega - \omega_0)$$

Step (no proofs, still true)

If x = 1, then

41/42

$$X(j\omega) = \frac{1}{j\omega} + \pi \delta(\omega)$$

(think of $1 = \lim_{\lambda \uparrow 0} \exp_{\lambda} 1$ and $1 = 1 + \mathbb{P}_{-1} 1$ as a kind of weak rationale).

Consequence:
- if
$$y(t) = \int_{-\infty}^{t} x(t) dt$$
, then
 $Y(j\omega) = \frac{1}{j\omega} X(j\omega) + \pi X(0)\delta(\omega)$

because y = 1 * x (Lect. 2, Slide 12), the convolution property of the Fourier transform, and the fact that $x\delta = x(0)\delta$ (Lect. 2, Slide 16).