

Linear Systems (034032)

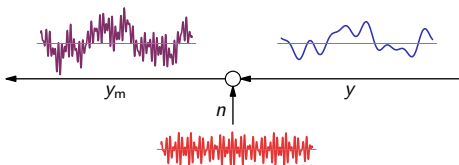
lecture no. 3

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Example 0



A signal y is observed via an imperfect sensor, where the measured signal is

$$y_m = y + n$$

for (unknown) additive noise n reflecting sensor inaccuracies. The question then is

- how signal (y) can be recovered from its corrupt measurements (y_m)?

This might appear a tough task, for there is no way we can separate y from n in the time domain . . .

Outline

Fourier series

Fourier transform

Fourier transforms of some standard signals

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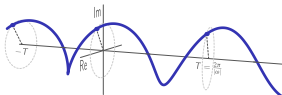
Fourier series

Fourier transform

Fourier transforms of some standard signals

Harmonic signal

Signal $\alpha = a \exp_{j\omega} : \mathbb{R} \rightarrow \mathbb{C}$,

$$\alpha(t) = ae^{j\omega t} = |a|e^{j(\omega t + \arg(a))} =$$


for $a \in \mathbb{C}$ and $\omega \in \mathbb{R}$ is called **harmonic signal** with frequency ω , amplitude $|a|$, and initial phase $\arg(a)$. Because

$$\alpha(t + \frac{2\pi}{\omega} k) = ae^{j\omega(t + 2\pi k/\omega)} = ae^{j\omega t + j2\pi k} = ae^{j\omega t} e^{j2\pi k} = ae^{j\omega t} = \alpha(t)$$

for all $k \in \mathbb{Z}$, the harmonic signal is $\frac{2\pi}{|\omega|}$ -periodic (ω may be negative).

Euler's formula $e^{j\theta} = \cos\theta + j\sin\theta$ can be used to connect the (complex) harmonic signal with real sinusoids:

$$\sin(\omega t + \phi) = ae^{j\omega t} + \bar{a}e^{-j\omega t}, \quad a = 0.5e^{j(\phi - \pi/2)}$$

(harmonics with ω and $-\omega$ come together in real-valued signals).

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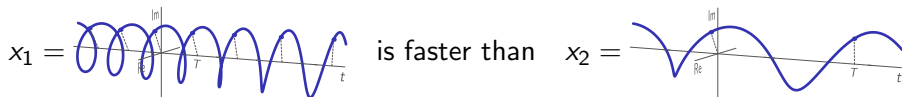
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Harmonic signal (contd)

The signal $a_1 \exp_{j\omega_1}$ is said to be faster (slower) than $a_2 \exp_{j\omega_2}$ if $|\omega_1| > |\omega_2|$ ($|\omega_1| < |\omega_2|$). Indeed,



just because

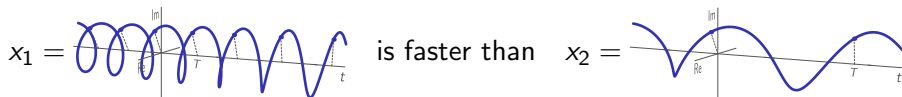
$$\frac{|\dot{x}_1(t)|}{|x_1(t)|} = |\omega_1| > |\omega_2| = \frac{|\dot{x}_2(t)|}{|x_2(t)|}, \quad \forall t$$

Note that there is no “the fastest” continuous-time signals.

$$P_{a \exp_{j\omega}} = \frac{1}{T} \int_0^T |a e^{j\omega t}|^2 dt = \frac{|a|^2}{T} \int_0^T dt = |a|^2$$

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Power

$$P_{a \exp_{j\omega}} = \frac{1}{T} \int_0^T |a e^{j\omega t}|^2 dt = \frac{|a|^2}{T} \int_0^T dt = |a|^2$$

Fourier series of continuous signals

If $x : \mathbb{R} \rightarrow \mathbb{R}$ is T -periodic and continuous, then at every t

$$x(t) = \sum_{k \in \mathbb{Z}} X[k] e^{j\omega_0 kt} = \sum_{k \in \mathbb{Z}} X[k] e^{j(2\pi/T)kt},$$

where

$$X[k] = \frac{1}{T} \int_{-T/2}^{T/2} x(t) e^{-j\omega_0 kt} dt = \frac{1}{T} \int_a^{a+T} x(t) e^{-j\omega_0 kt} dt \in \mathbb{C}$$

are known as **Fourier coefficients** of x and

$$\omega_0 := \frac{2\pi}{T}$$

is known as its **fundamental frequency**. The T -periodic $x_N : \mathbb{R} \rightarrow \mathbb{R}$ with

$$x_N(t) := \sum_{k=-N}^N X[k] e^{j\omega_0 kt}$$

is known as a partial sum of the Fourier series of x .

Example 1

Let

$$x = \sum_{i \in \mathbb{Z}} \delta_{iT} \text{tent}_{T/2} =$$

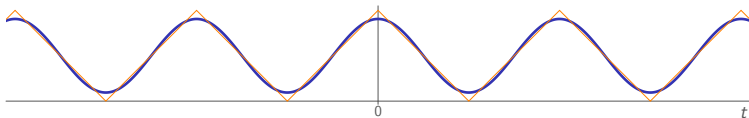
Fourier coefficients:

$$\begin{aligned} X[k] &= \frac{1}{T} \int_{-T/2}^{T/2} \text{tent}_{T/2}(t) e^{-j\omega_0 kt} dt = \frac{1}{T} \int_{-T/2}^{T/2} \left(1 - \frac{2|t|}{T}\right) e^{-j\omega_0 kt} dt \\ &= \frac{1}{T} \left(\int_{-T/2}^0 \left(1 + \frac{2t}{T}\right) e^{-j\omega_0 kt} dt + \int_0^{T/2} \left(1 - \frac{2t}{T}\right) e^{-j\omega_0 kt} dt \right) \\ &= \frac{1}{T} \left(\frac{(1 - e^{j\pi k} + j\pi k)T}{2\pi^2 k^2} + \frac{(1 - e^{-j\pi k} - j\pi k)T}{2\pi^2 k^2} \right) \\ &= \frac{1 - \cos(\pi k)}{\pi^2 k^2} = \frac{1 - (-1)^k}{\pi^2 k^2} = \begin{cases} 1/2 & \text{if } k = 0 \\ 0 & \text{if } k \neq 0 \text{ and is even} \\ 2/(\pi k)^2 & \text{if } k \text{ is odd} \end{cases} \end{aligned}$$

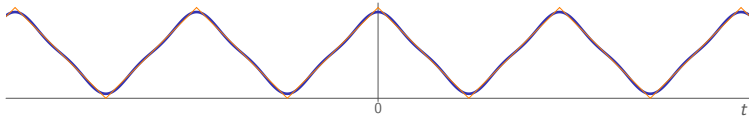
Example 1 (contd)

Partial sums:

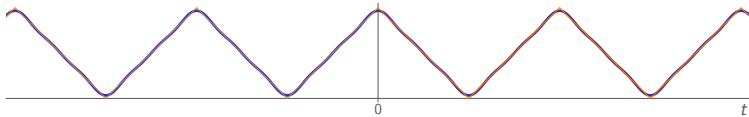
$N = 1 :$



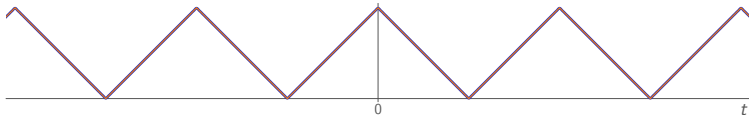
$N = 3 :$



$N = 5 :$



$N = 51 :$



Example 2

Let

$$s(t) = \begin{cases} 8t^2 & \text{if } 0 \leq t \leq 1/4 \\ -8t^2 + 8t - 1 & \text{if } 1/4 \leq t \leq 3/4 \\ 8(t-1)^2 & \text{if } 3/4 \leq t \leq 1 \\ 0 & \text{otherwise} \end{cases}$$

and define T -periodic

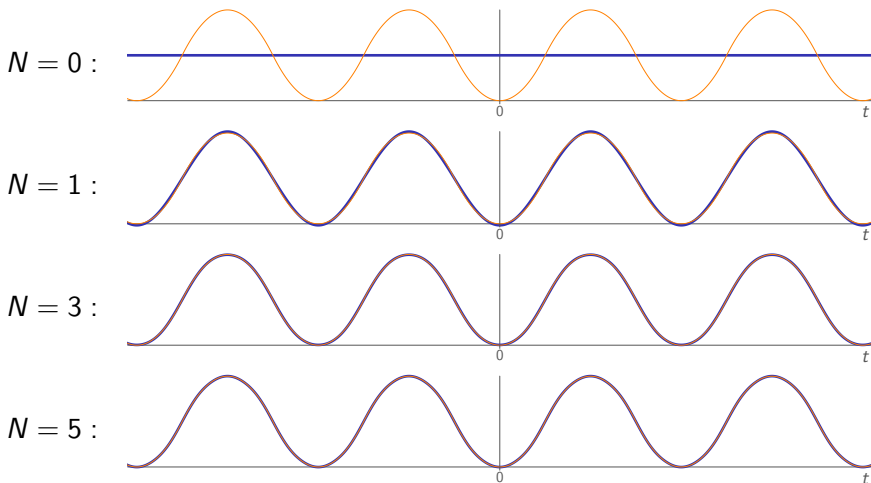
$$x = \sum_{i \in \mathbb{Z}} \delta_{iT} \mathbb{P}_{1/T} s =$$


Fourier coefficients:

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Example 2 (contd)

Partial sums:



Piecewise-smooth signals

A T -periodic signal x is said to be **piecewise smooth** if it's differentiable and has continuous derivative everywhere on $[0, T]$ with a possible exception of a finite number of distinct t_i , at which $x(t_i^+)$, $x(t_i^-)$, $\dot{x}(t_i^+)$ and $\dot{x}(t_i^-)$ exist in the sense of the existence of

$$x(t_i^+) := \lim_{h \downarrow 0} x(t_i + h), \quad x(t_i^-) := \lim_{h \downarrow 0} x(t_i - h), \quad \text{etc}$$

Example:

$$x = \sum_{i \in \mathbb{Z}} \mathcal{S}_{(i-\eta/2)T} \text{rect}_{\eta T} = \text{[Graph of a periodic square wave signal]}$$

for $\eta \in (0, 1)$.

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Remark The notion extends to non-periodic functions, which are ∞ -periodic, in a sense. In that case we need continuous derivatives everywhere except a counted number points t_i , at which $x(t_i^+)$, $x(t_i^-)$, $\dot{x}(t_i^+)$ and $\dot{x}(t_i^-)$ exist.

Fourier series of piecewise-smooth signals

Everything you always wanted to know about Fourier peculiarities* (*but were afraid to ask)

If $x : \mathbb{R} \rightarrow \mathbb{R}$ is T -periodic and piecewise smooth, then at every t

$$\frac{x(t^+) + x(t^-)}{2} = \sum_{k \in \mathbb{Z}} X[k] e^{j\omega_0 kt}$$

Let $X : \mathbb{Z} \rightarrow \mathbb{C}$ be the signal comprising the Fourier coefficients. If $X \in \ell_1$, then

$$\lim_{N \rightarrow \infty} x_N(t) = \lim_{N \rightarrow \infty} \sum_{k=-N}^N X[k] e^{j\omega_0 kt}$$

converges to $x(t)$ at every t and the limit is necessarily continuous

$X \notin \ell_1$, then the partial sum converges only in the ℓ_2 sense, i.e.

$$\lim_{N \rightarrow \infty} \|x - x_N\|_2 = 0$$

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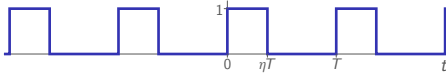
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Example 3

Let

$$x = \sum_{i \in \mathbb{Z}} \delta_{(i-\eta/2)T} \text{rect}_{\eta T} = \text{img}$$


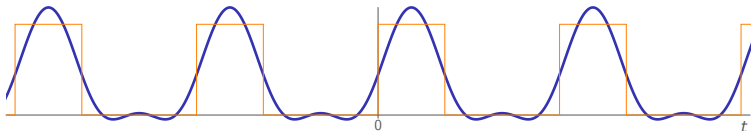
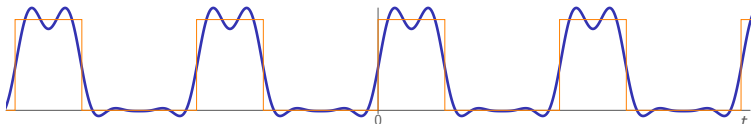
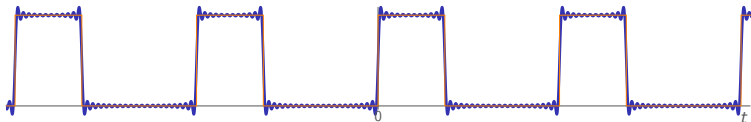
Fourier coefficients:

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(with $X[0] = \eta$).

Example 3 (contd)

Partial sums:

 $N = 1 :$  $N = 2 :$  $N = 5 :$  $N = 33 :$ 

Gibbs phenomenon

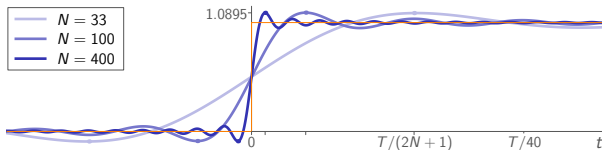
Near every discontinuity point of x ,

$$x_N\left(t + \frac{T}{2N+1}\right) - x(t^+) \xrightarrow{N \rightarrow \infty} \underbrace{\left(\frac{1}{\pi} \int_0^\pi \text{sinc}(t) dt - \frac{1}{2}\right)}_{\approx 0.089549} (x(t^+) - x(t^-))$$

and

$$x_N\left(t - \frac{T}{2N+1}\right) - x(t^-) \xrightarrow{N \rightarrow \infty} \left(\frac{1}{\pi} \int_0^\pi \text{sinc}(t) dt - \frac{1}{2}\right) (x(t^-) - x(t^+))$$

like in



Some properties

property	signal	Fourier coefficients
linearity	$x = a_1x_1 + a_2x_2$	$X[k] = a_1X_1[k] + a_2X_2[k]$
time shift	$y = \mathcal{S}_\tau x$	$Y[k] = e^{j\omega_0\tau k} X[k]$
time reversal	$y = \mathcal{P}_{-1}x$	$Y[k] = X[-k]$
conjugation	$y = \bar{x}$	$Y[k] = \overline{X[-k]}$
convolution	$z = x * y$	$Z[k] = X[k]Y[k]$

Consequently, if x is real-valued (codomain is \mathbb{R}), then $X[k] = \overline{X[-k]}$

– i.e. $|X[k]| = |X[-k]|$ and $\arg(X[k]) = -\arg(X[-k])$

and all information is in $X[k]$ for $k \in \mathbb{Z}_+$.

Remember, $(\mathcal{S}_\tau x)(t) = x(t + \tau)$ and $(\mathcal{P}_\zeta x)(t) = x(\zeta t)$.

Meaning

The expansion

$$x(t) = \sum_{k \in \mathbb{Z}} X[k] e^{j\omega_0 kt}$$

means that every T -periodic x is a superposition of elementary harmonics

$$\alpha_{x,k}(t) := X[k] e^{j\omega_0 kt}$$

whose frequencies are multiples of the fundamental frequency $\omega_0 = 2\pi/T$.

The discrete signal $X: \mathbb{Z} \rightarrow \mathbb{C}$ comprised of Fourier coefficients is known as the (line) spectrum of x . In other words,

$\Leftrightarrow T$ -periodic x can be equivalently represented by the discrete-time X , known as the frequency-domain representation of x .

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Parseval identity

Theorem

If T -periodic x is piecewise smooth, then

$$P_x = \sum_{k \in \mathbb{Z}} |X[k]|^2.$$

Proof: Because $|c|^2 = c\bar{c}$,

$$\begin{aligned} P_x &= \frac{1}{T} \int_{-T/2}^{T/2} x(t) \overline{x(t)} dt = \frac{1}{T} \int_{-T/2}^{T/2} x(t) \overline{\left(\sum_{k \in \mathbb{Z}} X[k] e^{j\omega_0 kt} \right)} dt \\ &= \sum_{k \in \mathbb{Z}} \left(\frac{1}{T} \int_{-T/2}^{T/2} x(t) e^{-j\omega_0 kt} dt \right) \overline{X[k]} \\ &= \sum_{k \in \mathbb{Z}} X[k] \overline{X[k]} = \sum_{k \in \mathbb{Z}} |X[k]|^2 \end{aligned}$$



Parseval identity: meaning

The Parseval identity effectively says that

$$P_x = \sum_{k \in \mathbb{Z}} P_{\alpha_{x,k}}$$

i.e. the power of x equals the sum of powers of all its harmonic components in the expansion $x = \sum_k \alpha_{x,k}$. This, in turn, implies that

- harmonics with largest amplitudes dominate the behavior of x

– if dominating harmonics are low, x is slow



– if dominating harmonics are high, x is fast



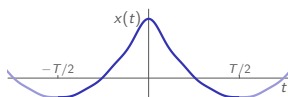
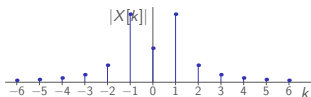
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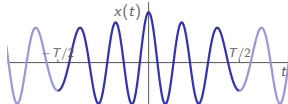
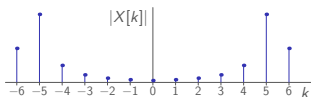
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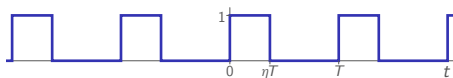


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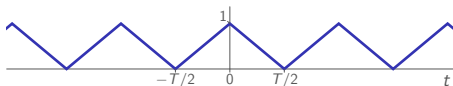


Decay of Fourier coefficients

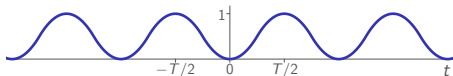
In general, the faster $|X[k]|$ decays as $|k|$ grows, the smoother x is, because faster harmonics have then smaller effect on x , cf.



$$\longrightarrow |X[k]| = \frac{\sin(\pi \eta k)}{\pi |k|}$$



$$\longrightarrow |X[k]| = \frac{1 - \cos(\pi k)}{\pi^2 k^2}$$



$$\longrightarrow |X[k]| = \frac{8|\sin(\pi k/2)|}{\pi^3 |k|^3}$$

Outline

Fourier series

Fourier transform

Fourier transforms of some standard signals

Definition

The **Fourier transform** $\mathfrak{F}\{x\}$ of a signal x is the signal $X : \mathbb{R} \rightarrow \mathbb{C}$ such that

$$X(j\omega) = (\mathfrak{F}\{x\})(j\omega) := \int_{\mathbb{R}} x(t)e^{-j\omega t} dt$$

('j ω ' is used for a technical reason to be clarified one day). It is well defined if $x \in L_1$ (plus some mild technical assumptions) and then

$$x(t) = \frac{1}{2\pi} \int_{\mathbb{R}} X(j\omega)e^{j\omega t} d\omega =: (\mathfrak{F}^{-1}\{X\})(t)$$

at every t . The latter integral is referred to as the **inverse Fourier transform**.

If $x \in L_2$, then the Fourier integral converges only in the (weaker) L_2 -norm sense, $\|x - \mathfrak{F}^{-1}\{X_N\}\|_2 \rightarrow 0$. We can then still extend the transform to L_2 signals. The use of distributions facilitates extending the Fourier transform to yet wider classes of signals.

Meaning

Similarly to the Fourier series, the relation

$$x(t) = \frac{1}{2\pi} \int_{\mathbb{R}} X(j\omega) e^{j\omega t} d\omega$$

means that

- aperiodic x is also a superposition of elementary harmonics $\alpha_{x,\omega}$, with $\alpha_{x,\omega}(t) = \frac{1}{2\pi} X(j\omega) e^{j\omega t}$,

now with a continuum of frequencies ω (measured in radians per time unit).

The signal X is then called the spectrum or frequency-domain representation of x , with the amplitude spectrum $|X|$ and the phase spectrum $\arg(X)$.

The value $X(j0) = X(0)$ is the average of x over all its domain, i.e. \mathbb{R} .

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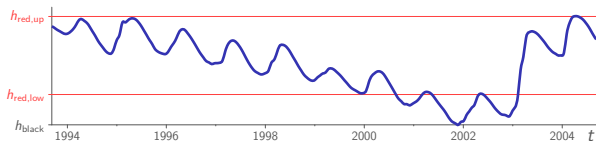
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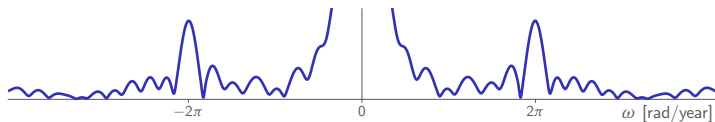
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Example 1

Kinneret water level from Sep 1993 to Sep 2004



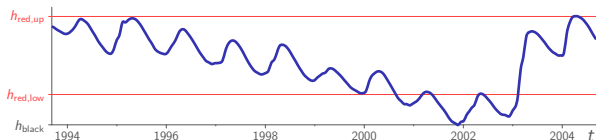
and its amplitude spectrum (with $h_{\text{red,up}}$ taken as zero)



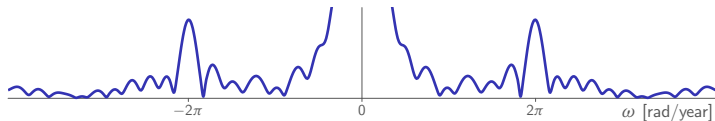
Peaks at $\omega = \pm 2\pi$ [rad/year] reflect the annual cycle.

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Kinneret water level from Sep 1993 to Sep 2004



and its amplitude spectrum (with $h_{\text{red,up}}$ taken as zero)



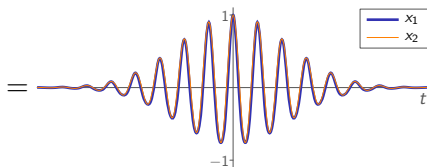
Peaks at $\omega = \pm 2\pi$ [rad/year] reflect the annual cycle.

Example 2

Two L_1 signals x_1 and x_2 , with

$$x_1(t) = \frac{8 \cos(2\pi t) + \cos(4\pi t)}{9} e^{-t^2/10}$$

$$x_2(t) = \frac{8 \cos(2\pi t) + 1}{9} e^{-t^2/10}$$



are hardly distinguishable in the time domain. But they are quite different, e.g. the average $\int_{\mathbb{R}} x_1(t) dt \approx 0 \neq 0.62 \approx \int_{\mathbb{R}} x_2(t) dt$.

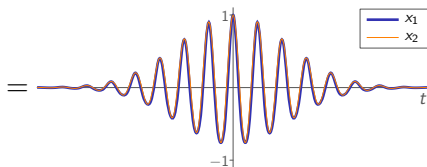
These differences are visible in their spectra

Example 2

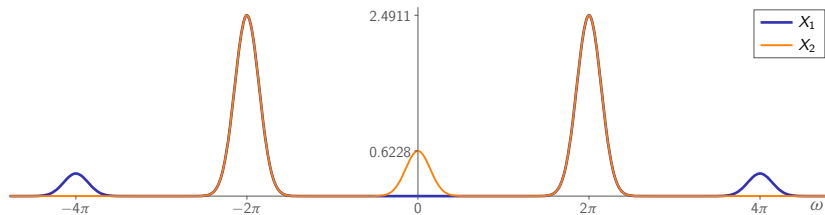
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$$x_1(t) = \frac{8 \cos(2\pi t) + \cos(4\pi t)}{9} e^{-t^2/10}$$

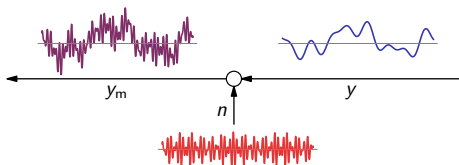
$$x_2(t) = \frac{8 \cos(2\pi t) + 1}{9} e^{-t^2/10}$$



are hardly distinguishable in the time domain. But they are quite different, e.g. the average $\int_{\mathbb{R}} x_1(t) dt \approx 0 \neq 0.62 \approx \int_{\mathbb{R}} x_2(t) dt$. These differences are visible in their spectra



Example 0 (contd)



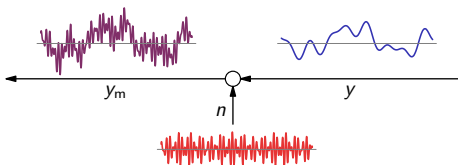
The question was

- how signal (y) can be recovered from its corrupt measurements (y_m)?

This might appear a tough task, for there is no way we can separate y from n in the time domain... But in the frequency domain these signals are well separated,

suggesting that the frequency-domain viewpoint is valuable¹.

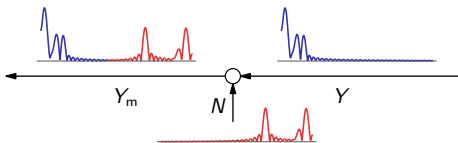
Example 0 (contd)



The question was

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This might appear a tough task, for there is no way we can separate y from n in the time domain... But in the frequency domain these signals are well separated,



suggesting that the frequency-domain viewpoint is valuable¹.

¹However, we yet to learn how to fully exploit it efficiently.

Basic properties

property	time domain	frequency domain
linearity	$x = a_1x_1 + a_2x_2$	$X(j\omega) = a_1X_1(j\omega) + a_2X_2(j\omega)$
duality	$y = X _{\omega=t}$	$Y(j\omega) = 2\pi x(-\omega)$
time shift	$y = \mathcal{S}_\tau x$	$Y(j\omega) = e^{j\omega\tau} X(j\omega)$
time scaling	$y = \mathcal{P}_\zeta x$	$Y(j\omega) = \frac{1}{ \zeta } X(j\omega/\zeta)$
conjugation	$y = \bar{x}$	$Y(j\omega) = \overline{X(-j\omega)}$
modulation	$y = x \exp_{j\omega_0}$	$Y(j\omega) = X(j(\omega - \omega_0))$
differentiation ²	$y = \dot{x}$	$Y(j\omega) = j\omega X(j\omega)$
convolution	$z = x * y$	$Z(j\omega) = X(j\omega)Y(j\omega)$

... provided all involved transforms exist

²If $\lim_{t \rightarrow \pm\infty} x(t) = 0$, which is normally the case for $x \in L_1$.

Basic properties: duality

If $y = X|_{\omega=t}$, i.e. $y(t) = X(jt)$, where $X = \mathfrak{F}\{x\}$, then

$$\begin{aligned} Y(j\omega) &= \int_{\mathbb{R}} X(jt) e^{-j\omega t} dt \Big|_{t=\tilde{\omega}} = 2\pi \left(\frac{1}{2\pi} \int_{\mathbb{R}} X(j\tilde{\omega}) e^{j\tilde{\omega}(-\omega)} d\tilde{\omega} \right) \\ &= 2\pi x(-\omega) \end{aligned}$$

because

$$x(t) = \frac{1}{2\pi} \int_{\mathbb{R}} X(j\omega) e^{j\omega t} d\omega$$

Basic properties: time shift

If $y = \mathcal{S}_\tau x$, i.e. $y(t) = x(t + \tau)$, then

$$\begin{aligned} Y(j\omega) &= \int_{\mathbb{R}} x(t + \tau) e^{-j\omega t} dt \Big|_{s=t+\tau} = \int_{\mathbb{R}} x(s) e^{-j\omega(s-\tau)} ds \\ &= e^{j\omega\tau} \int_{\mathbb{R}} x(s) e^{-j\omega s} ds \\ &= e^{j\omega\tau} X(j\omega) \end{aligned}$$

Basic properties: time scaling

If $y = \mathbb{P}_\zeta x$, i.e. $y(t) = x(\zeta t)$, then

$$\begin{aligned}
 Y(j\omega) &= \int_{\mathbb{R}} x(\zeta t) e^{-j\omega t} dt \Big|_{s=\zeta t} = \begin{cases} \int_{-\infty}^{\infty} x(s) e^{-j\omega s/\zeta} d(s/\zeta) & \text{if } \zeta > 0 \\ \int_{\infty}^{-\infty} x(s) e^{-j\omega s/\zeta} d(s/\zeta) & \text{if } \zeta < 0 \end{cases} \\
 &= \begin{cases} \frac{1}{\zeta} \int_{-\infty}^{\infty} x(s) e^{-j(\omega/\zeta)s} ds & \text{if } \zeta > 0 \\ -\frac{1}{\zeta} \int_{-\infty}^{\infty} x(s) e^{-j(\omega/\zeta)s} ds & \text{if } \zeta < 0 \end{cases} \\
 &= \frac{1}{|\zeta|} \int_{\mathbb{R}} x(s) e^{-j(\omega/\zeta)s} ds \\
 &= \frac{1}{|\zeta|} X(j\omega/\zeta)
 \end{aligned}$$

Basic properties: conjugation

If $y = \bar{x}$ (complex conjugate), then

$$\begin{aligned} Y(j\omega) &= \int_{\mathbb{R}} \overline{x(t)} e^{-j\omega t} dt = \int_{\mathbb{R}} \overline{x(t) e^{-j\omega t}} dt = \overline{\int_{\mathbb{R}} x(t) e^{j\omega t} dt} \\ &= \overline{\int_{\mathbb{R}} x(t) e^{-j(-\omega)t} dt} \\ &= \overline{X(-j\omega)} \end{aligned}$$

If $x : \mathbb{R} \rightarrow \mathbb{R}$ (real valued), then $y = \bar{x} = x$, so that

$$X(j\omega) = \overline{X(-j\omega)},$$

i.e. we may look only at the spectrum over $\omega \geq 0$. If, in addition, $x = \mathbb{P}_{-1}x$ (such functions are called *even*), then by the time scaling property

$$X(j\omega) = X(-j\omega) = \overline{X(-j\omega)}.$$

Hence, if x is real valued and even, then X is real valued and even as well.

Basic properties: modulation

If $y = x \exp_{j\omega_0}$, i.e. $y(t) = x(t)e^{j\omega_0 t}$, then

$$\begin{aligned} Y(j\omega) &= \int_{\mathbb{R}} x(t)e^{j\omega_0 t} e^{-j\omega t} dt = \int_{\mathbb{R}} x(t)e^{-j(\omega - \omega_0)t} dt \\ &= X(j(\omega - \omega_0)) \end{aligned}$$

By linearity and modulation, if

$$y(t) = \sin(\omega_0 t + \phi)x(t) = ae^{j\omega_0 t}x(t) + \bar{a}e^{-j\omega_0 t}x(t),$$

where $a := 0.5e^{j(\phi - \pi/2)}$, then

$$Y(j\omega) = aX(j(\omega - \omega_0)) + \bar{a}X(j(\omega + \omega_0))$$

Basic properties: differentiation

If $y = \dot{x}$, i.e. $y(t) = \frac{d}{dt}x(t)$, and $\lim_{t \rightarrow \pm\infty} x(t) = 0$, then

$$\begin{aligned} Y(j\omega) &= \int_{\mathbb{R}} \dot{x}(t) e^{-j\omega t} dt = x(t) e^{-j\omega t} \Big|_{-\infty}^{\infty} - \int_{\mathbb{R}} x(s) \left(\frac{d}{dt} e^{-j\omega t} \right) dt \\ &= j\omega \int_{\mathbb{R}} x(t) e^{-j\omega t} dt \\ &= j\omega X(j\omega) \end{aligned}$$

because

$$\int_a^b \dot{f}(t) g(t) dt = f(t) g(t) \Big|_a^b - \int_a^b f(t) \dot{g}(t) dt$$

(integration by parts).

Similar arguments apply to the inverse Fourier, so

$$y(t) = -jtx(t) \iff Y(j\omega) = \frac{d}{d\omega} X(j\omega)$$

Basic properties: convolution

If $z = x * y$, then

$$\begin{aligned}
 Z(j\omega) &= \int_{\mathbb{R}} \int_{\mathbb{R}} x(t-s)y(s)ds e^{-j\omega t} dt = \int_{\mathbb{R}} \int_{\mathbb{R}} x(t-s)y(s)e^{-j\omega t} dt ds \\
 &= \int_{\mathbb{R}} \underbrace{\int_{\mathbb{R}} x(t-s)e^{-j\omega t} dt}_{\mathfrak{F}\{\mathcal{S}_{-s}x\}} y(s) ds \\
 &= \int_{\mathbb{R}} X(j\omega)e^{-j\omega s} y(s) ds && \text{(by the time shift property)} \\
 &= X(j\omega) \int_{\mathbb{R}} y(s)e^{-j\omega s} ds \\
 &= X(j\omega)Y(j\omega)
 \end{aligned}$$

the (unproven) fact that $x, y \in L_1 \implies x * y \in L_1$ is required in this proof.

Parseval's theorem

Theorem

If $x \in L_1 \cap L_2$, then

$$\|x\|_2^2 = \int_{\mathbb{R}} |x(t)|^2 dt = \frac{1}{2\pi} \int_{\mathbb{R}} |X(j\omega)|^2 d\omega = \frac{1}{2\pi} \|X\|_2^2$$

In other words,

- the energy of x equals the energy of $\mathfrak{F}\{x\}$, modulo the factor $1/(2\pi)$.

Outline


Fourier series

Fourier transform

Fourier transforms of some standard signals

Rectangular pulse

If $x = \text{rect}$, then

$$\begin{aligned}
 X(j\omega) &= \int_{\mathbb{R}} x(t)e^{-j\omega t} dt = \int_{-1/2}^{1/2} e^{-j\omega t} dt = \left. \frac{e^{-j\omega t}}{-j\omega} \right|_{-1/2}^{1/2} = \frac{e^{j\omega/2} - e^{-j\omega/2}}{j\omega} \\
 &= \frac{e^{j\omega/2} - e^{-j\omega/2}}{2j\omega/2} = \frac{\sin(\omega/2)}{\omega/2} = \text{sinc}(\omega/2) =
 \end{aligned}$$


Consequences:

– by time scaling, if $y = \text{rect}_a$ for some $a > 0$, then

$$Y(j\omega) = (\mathcal{F}\{\mathbb{P}_{1/a} \text{rect}\})(\omega) = a \text{sinc}\left(\frac{\omega}{a}\right) = a(\mathbb{P}_{1/2} \text{sinc})(\omega)$$


– by duality and time scaling, if $y = \mathbb{P}_{1/2} \text{sinc}$ and $z = \mathbb{P}_c \text{sinc}$, then

$$Y(j\omega) = 2\pi \text{rect}(\omega) \quad \text{and} \quad Z(j\omega) = \frac{\pi}{c} \text{rect}_{2c}(\omega)$$

– $\text{rect}_a \text{rect}_b = \text{rect}_{\min\{a,b\}}$, $\text{sinc} \text{sinc} = \text{sinc}$ (see exercise 10)

Rectangular pulse

If $x = \text{rect}$, then

$$\begin{aligned} X(j\omega) &= \int_{\mathbb{R}} x(t)e^{-j\omega t} dt = \int_{-1/2}^{1/2} e^{-j\omega t} dt = \left. \frac{e^{-j\omega t}}{-j\omega} \right|_{-1/2}^{1/2} = \frac{e^{j\omega/2} - e^{-j\omega/2}}{j\omega} \\ &= \frac{e^{j\omega/2} - e^{-j\omega/2}}{2j\omega/2} = \frac{\sin(\omega/2)}{\omega/2} = \text{sinc}(\omega/2) \end{aligned}$$


Consequences:

- by time scaling, if $y = \text{rect}_a$ for some $a > 0$, then

$$Y(j\omega) = (\mathfrak{F}\{\mathbb{P}_{1/a} \text{rect}\})(\omega) = a \text{sinc}\left(\frac{a}{2}\omega\right) = a(\mathbb{P}_{1/2} \text{sinc})(\omega)$$

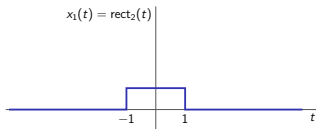
- by duality and time scaling, if $y = \mathbb{P}_{1/2} \text{sinc}$ and $z = \mathbb{P}_\zeta \text{sinc}$, then

$$Y(j\omega) = 2\pi \text{rect}(\omega) \quad \text{and} \quad Z(j\omega) = \frac{\pi}{\zeta} \text{rect}_{2\zeta}(\omega)$$

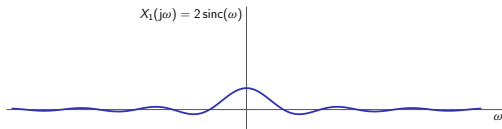
(mind that $\text{rect}(-\omega) = \text{rect}(\omega)$ and $\mathbb{P}_\zeta \text{sinc} = \mathbb{P}_{2\zeta} \mathbb{P}_{1/2} \text{sinc}$).

Rectangular pulse: examples

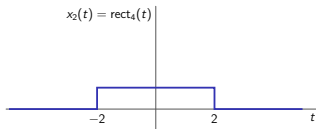
$$x_1(t) = \text{rect}_2(t)$$



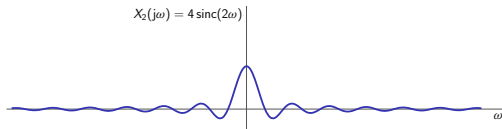
$$X_1(j\omega) = 2 \text{sinc}(\omega)$$



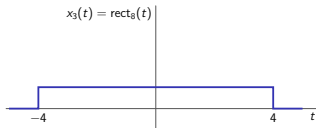
$$x_2(t) = \text{rect}_4(t)$$



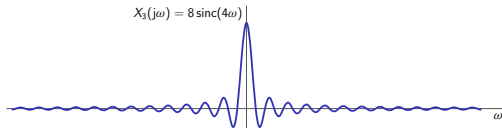
$$X_2(j\omega) = 4 \text{sinc}(2\omega)$$



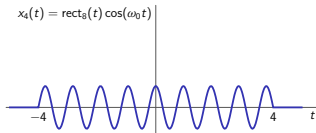
$$x_3(t) = \text{rect}_8(t)$$



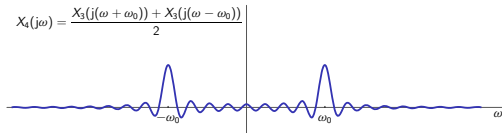
$$X_3(j\omega) = 8 \text{sinc}(4\omega)$$



$$x_4(t) = \text{rect}_8(t) \cos(\omega_0 t)$$




$$X_4(j\omega) = \frac{X_3(j(\omega + \omega_0)) + X_3(j(\omega - \omega_0))}{2}$$



Triangular pulse

Remember (Lect. 2, Slide 12) that tent = rect * rect. So if $x = \text{tent}$, then

$$X(j\omega) = (\mathcal{F}\{\text{rect} * \text{rect}\})(j\omega) = \text{sinc}^2(\omega/2) =$$


by the convolution property of the Fourier transform.


Consequence:

– by time scaling, if $y = \text{tent}_a$ for some $a > 0$, then

$$Y(j\omega) = (\mathcal{F}\{P_{1/a} \text{tent}\})(\omega) = a \text{sinc}^2(\frac{\omega}{2})$$

Triangular pulse

Remember (Lect. 2, Slide 12) that $\text{tent} = \text{rect} * \text{rect}$. So if $x = \text{tent}$, then

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Exponent with support in \mathbb{R}_+

If $x = \exp_{\lambda} \mathbb{1}$ for $\lambda \in \mathbb{R}$, then $x \in L_1$ iff $\lambda < 0$ and in that case

$$X(j\omega) = \int_{\mathbb{R}} e^{\lambda t} \mathbb{1}(t) e^{-j\omega t} dt = \int_{\mathbb{R}_+} e^{(\lambda - j\omega)t} dt = \frac{e^{(\lambda - j\omega)t}}{\lambda - j\omega} \Big|_0^{\infty} = \frac{1}{j\omega - \lambda}$$

The same formula holds if $\lambda \in \mathbb{C}$ and $\operatorname{Re} \lambda < 0$.

Consequences:

– by differentiation with respect to frequency,

$$y(t) = \frac{t^n}{n!} e^{\lambda t} \mathbb{1}(t) \iff Y(j\omega) = \frac{1}{(j\omega - \lambda)^{n+1}}$$

– by linearity and modulation, if $y(t) = \sin(\omega_0 t + \phi) e^{\lambda t} \mathbb{1}(t)$, then

$$Y(j\omega) = \frac{\omega_0 \cos \phi + (j\omega - \lambda) \sin \phi}{(j\omega - \lambda)^2 + \omega_0^2}$$

Exponent with support in \mathbb{R}_+

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Dirac delta (not quite rigorous, still true)

If $x = \delta$, then by the sifting property

$$X(j\omega) = \int_{\mathbb{R}} \delta(t) e^{-j\omega t} dt = e^{-j\omega t} \Big|_{t=0} = 1$$

i.e. $\mathcal{F}\{\delta\}$ contains all harmonics with equal weights, $1/(2\pi)$.

Consequences:

→ by duality and the fact that $\delta(\omega) = \delta(-\omega)$, if $y = 1$ (constant), then

$$Y(j\omega) = 2\pi\delta(\omega)$$

→ by modulation, if $y = \exp_{j\omega_0}$, then

$$Y(j\omega) = 2\pi\delta(\omega - \omega_0)$$

→ by linearity, if $y(t) = \sin(\omega_0 t + \phi)$, then

$$Y(j\omega) = \pi e^{j(\pi/2 - \phi)} \delta(\omega + \omega_0) - \pi e^{j(\pi/2 + \phi)} \delta(\omega - \omega_0)$$

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Step (no proofs, still true)

If $x = \mathbb{1}$, then

$$X(j\omega) = \frac{1}{j\omega} + \pi\delta(\omega)$$

(think of $\mathbb{1} = \lim_{\lambda \uparrow 0} \exp_{\lambda} \mathbb{1}$ and $1 = \mathbb{1} + \mathbb{P}_{-1} \mathbb{1}$ as a kind of weak rationale).

Consequence:

if $y(t) = \int_{-\infty}^t x(t) dt$, then

$$Y(j\omega) = \frac{1}{j\omega} X(j\omega) + \pi X(0)\delta(\omega)$$

because $y = \mathbb{1} * x$ (lect. 2, slide 12), the convolution property of the Fourier transform, and the fact that $x\delta = x(0)\delta$ (lect. 2, slide 30).

Step (no proofs, still true)

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